Title	Find and repair electrical faults and perform test routines on robotic equipment		
Level	4	Credits	5

Purpose	This unit standard is for qualified electricians who need to attend to electrical faults in robotic equipment.
	People credited with this unit standard are able to: find and repair electrical faults in robots, associated input/output devices, and robotic safety circuits; and perform test routines on robotic equipment.
	on robotic equipment.

Classification	Mechanical Engineering > Engineering - Robotics

Available grade	Achieved	·S

## **Guidance Information**

 Legislation, codes of practice and standards relevant to this unit standard: Health and Safety in Employment Act 1992, and associated regulations; Electricity Act 1992;

Electricity Regulations 1997;

New Zealand Electrical Codes of Practice (Ministry of Commerce, ISSN 0114-0663); AS/NZS 3760:2001, In-service safety inspection and testing of electrical equipment; Safe Working Practices for Electricians and Electrical Workers, (Ministry of Commerce, 1990);

and their subsequent amendments and replacements.

2 Definitions

*Organisational procedures* refer to documents that include: worksite rules, codes, and practices; equipment maintenance instructions and status requirements; and health and safety requirements.

*Robotic equipment* for the purposes of this unit standard refers to robots, input/output devices, and safety circuits.

# Outcomes and performance criteria

## Outcome 1

Find and repair electrical faults and perform test routines on robots.

Range AC drive, DC drive.

## Performance criteria

1.1 Documentation for robot is assembled in the work area before fault diagnosis is commenced.

Range manufacturer's information, maintenance instructions, safety procedures.

- 1.2 Testing for faults is conducted in accordance with organisational procedures.
- 1.3 The cause/s of electrical faults are correctly diagnosed.
- 1.4 Robot is repaired and tested in accordance with organisational procedures.
- 1.5 Fault and repair details are documented in accordance with organisational procedures.

#### Outcome 2

Find and repair electrical faults and perform test routines on robotic input/output devices.

Range input, output.

#### **Performance criteria**

2.1 Documentation for input/output device is assembled in the work area before fault diagnosis is commenced.

Range manufacturer's information, maintenance instructions, safety procedures.

- 2.2 Testing for faults is conducted in accordance with organisational procedures.
- 2.3 The cause/s of electrical faults is/are correctly diagnosed.
- 2.4 Input/output device is repaired and tested in accordance with organisational procedures.
- 2.5 Fault and repair details are documented in accordance with organisational procedures.

## Outcome 3

Find and repair electrical faults and perform test routines on robotic safety circuits.

Range a minimum of two circuits.

## Performance criteria

3.1 Safety issues to be considered when working on hardwired emergency stop circuits are described.

- 3.2 Documentation for safety circuit is assembled in the work area before fault diagnosis is commenced.
  - manufacturer's information, maintenance instructions, safety Range procedures.
- 3.3 Testing for faults is conducted in accordance with organisational procedures.
- 3.4 The cause/s of electrical faults is/are correctly diagnosed.
- 3.5 Safety circuit is repaired and tested in accordance with organisational procedures.
- Fault and repair details are documented in accordance with organisational 3.6 procedures.

## This unit standard is expiring. Assessment against the standard must take place by the last date for assessment set out below.

## Status information and last date for assessment for superseded versions

Process	Version	Date	Last Date for Assessment	
Registration	1	26 August 2002	31 December 2026	
Review	2	26 September 2024	31 December 2026	

Consent and Moderation Requirements (CMR) reference	0013	
This CMR can be accessed at http://www.pzga.govt.pz/framework/search/index.do		